



# **Writing Assembly Code for the NetBurner ColdFire Platform**

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## ***Introduction***

So you want to write some assembly code for the NetBurner ColdFire platform. This is not meant to be a complete guide to assembly language programming for the ColdFire, but a minimal guide to get started. If you would like more information on assembly language programming for the ColdFire, then you can find references to a couple of books at the end of this document.

## ***Basic Rules***

- Parameters are passed on the stack.
- You can modify D0, D1, A0, A1, and the SR registers. Any other registers must be restored before returning.
- Return values are passed in D0.
- Functions must end with `rts`.

## ***Parameter Passing***

When a function is called, any input parameters are passed on the stack. The return address is then passed on the stack. The stack is stored in register A7.

## ***Simple Examples***

### ***Increment Function***

Suppose we want to write the following function:

```
int inc( int i )
{
    return i + 1;
}
```

In assembly, it would be written as the following:

```
.global inc
inc:
    move.l %a7@4,%d0    // Get the first parameter
    addq.l #1,%d0
    rts
```

## ***Subtraction Function***

Suppose we have two parameters:

```
int sub( int a, int b )
{
    return a - b;
}
```

a is the first parameter and it will be closest on the stack, followed by b being the next closest, etc...

```
.global sub
sub:
    move.l %a7@(4),%d0    // Value of a
    move.l %a7@(8),%d1    // Value of b
    sub.l  %d1,%d0
    rts
```

## ***Passing in Pointer-Type Parameters***

Suppose one or more of the parameters are pointers:

```
void asmstrcpy( char *dest, const char *source );
```

```
.global asmstrcpy
asmstrcpy:
    move.l %a7@(4),%a0    // Get the first parameter
    move.l %a7@(8),%a1    // Get the second parameter
asm_loop:
    move.b %a1@+,%d0      // Load char and increment address ptr
    move.b %d0,%a0@+      // Store char and increment address ptr
    bne asm_loop
    rts
```

## ***Accessing Global Variables***

```
DWORD getsecs( void );
```

The following accesses the global variable Secs:

```
.global getsecs
.extern Secs          // Define the global variable to access
getsecs:
    move.l Secs,%d0
    rts
```

## Calling Another Function

It is easy if the function being called takes no parameters:

```
.extern other_function
    jsr other_function
```

If the function being called takes parameters, then you must pass them clean up after yourself when the function returns.

Take the following test function for example:

```
void ShowParams( int P1, int P2 )
{
    iprintf( "P1 = %08x or %d    P2 = %08x or %d\r\n", P1, P1, P2, P2 );
}
```

Then call it from assembly language:

```
.global TestAsmCall
.extern ShowParams
TestAsmCall:
    move.l #1,%d0
    move.l %d0,%a7@-    // Push the second parameter on the stack
    move.l #2,%d0
    move.l %d0,%a7@-    // Push the first parameter on the stack
    jsr ShowParams
    addq.l #8,%a7        // Take the parameters back off the stack
    rts
```

## Inline or as a Separate File

You have been shown some simple code, but have not yet defined how to get it into your program. You can do it in two ways: as inline assembly or as a separate assembly file.

### Inline Assembly

Below is a project that defines all of the functions above as inline assembly. Note that the functions must be declared as extern C so that C++ can find them. Also note that all the functions must "live" someplace and that they are all defined in a function named `Holderfunc` (the name of this function does not matter).

```

#include "predef.h"
#include <stdio.h>
#include <ctype.h>
#include <startnet.h>
#include <autoupdate.h>
#include <dhcpcclient.h>
#include <bsp.h>

extern "C" {
    void UserMain( void *pd );
}

const char *AppName = "ftest";

extern "C" {
    int inc( int i );
    int sub( int a, int b );
    void asmstrcpy( char *dest, const char *source );
    DWORD getsecs( void );
    void ShowParams( int P1, int P2 );
    void TestAsmCall();
}

void ShowParams( int P1, int P2 ) {
    iprintf( "P1 = %08x or %d    P2 = %08x or %d\r\n", P1, P1, P2, P2 );
}

void Holderfunc() {
    /* inc function */
    asm(".global inc                ");
    asm("inc:                       ");
    asm("    move.l %a7@(4),%d0 "); // Get the first parameter
    asm("    addq.l #1,%d0      ");
    asm("    rts                ");

    /* sub function */
    asm(".global sub                ");
    asm("sub:                       ");
    asm("    move.l %a7@(4),%d0 "); // Get the first parameter
    asm("    move.l %a7@(8),%d1 "); // Get the second parameter
    asm("    sub.l  %d1,%d0      ");
    asm("    rts                ");

    /* asmstrcpy function */
    asm(".global asmstrcpy          ");
    asm("asmstrcpy:                 ");
    asm("    move.l %a7@(4),%a0 "); // Get the first parameter
    asm("    move.l %a7@(8),%a1 "); // Get the second parameter
    asm("asm_loop:                  ");
    asm("    move.b %a1@+,%d0  "); // Load char & increment address ptr
    asm("    move.b %d0,%a0@+  "); // Store char & increment address ptr
    asm("    bne asm_loop      ");
}

```

```

asm("    rts                ");

/* getsecs function */
asm(".global getsecs        ");
asm(".extern Secs           "); // Define global variable to access
asm("getsecs:              ");
asm("    move.l Secs,%d0    ");
asm("    rts                ");

/* TestAsmCall function */
asm(".global TestAsmCall    ");
asm(".extern ShowParams     ");
asm("TestAsmCall:          ");
asm("    move.l #1,%d0      ");
asm("    move.l %d0,%a7@-   "); // Push 2nd parameter on the stack
asm("    move.l #2,%d0      ");
asm("    move.l %d0,%a7@-   "); // Push 1st parameter on the stack
asm("    jsr ShowParams     ");
asm("    addq.l #8,%a7      "); // Take parameters back off the stack
asm("    rts                ");
}

void UserMain( void *pd ) {
    // Set up the TCP/IP stack buffers, etc...
    InitializeStack();

    // Get a DHCP address if needed. You may want to add a check for the
    // return value from this function. See the function definition in
    // \Nburn\include\dhcpclient.h.
    GetDHCPAddressIfNecessary();

    // Change our priority from highest to something in the middle.
    OSChangePrio( MAIN_PRIO );

    // Enable the ability to update code over the network.
    EnableAutoUpdate();

    iprintf( "Application started\n" );

    char buffer[20];

    while ( 1 )
    {
        OSTimeDly( 20 );
        iprintf( "inc(25) = %ld\r\n", inc( 25 ) );
        iprintf( "sub(5,4) = %ld\r\n", sub( 5, 4 ) );
        asmstrcpy( buffer, "Test" );
        iprintf( "buffer[%s]\r\n", buffer );
        iprintf( "getsecs = %ld, Secs = %ld\r\n", getsecs(), Secs );
        TestAsmCall();
    }
}

```

## Separate Assembly File

To put your assembly code in a separate file, put it all in a file ending with a ".s" extension such as "myasm.s", and then add it to the ASRCS area of your makefile like this:

```
ASRCS := myasm.s
```

The "myasm.s" file:

```
/****** Start of myasm.s *****/

.text

/* inc function */
.global inc
inc:
    move.l %a7@(4),%d0    /* Get the first parameter */
    addq.l #1,%d0
    rts

/* sub function */
.global sub
sub:
    move.l %a7@(4),%d0    /* Get the first parameter */
    move.l %a7@(8),%d1    /* Get the second parameter */
    sub.l %d1,%d0
    rts

/* asmstrcpy function */
.global asmstrcpy
asmstrcpy:
    move.l %a7@(4),%a0    /* Get the first parameter */
    move.l %a7@(8),%a1    /* Get the second parameter */
asm_loop:
    move.b %a1@+,%d0      /* Load char and increment address pointer */
    move.b %d0,%a0@+      /* Store char and increment address pointer */
    bne asm_loop
    rts

/* getsecs function */
.global getsecs
.extern Secs              /* Define the global variable to access */
getsecs:
    move.l Secs,%d0
    rts

/* TestAsmCall function */
.global TestAsmCall
.extern ShowParams
TestAsmCall:
    move.l #1,%d0
    move.l %d0,%a7@-      /* Push the second parameter on the stack */
    move.l #2,%d0
    move.l %d0,%a7@-      /* Push the first parameter on the stack */
```



```
jsr ShowParams
addq.l #8,%a7      /* Take the parameters back off the stack */
rts

/***** End of myasm.s *****/
```

## ***ColdFire Assembly Programming References***

ColdFire Family Programmer's Reference Manual - Revision 3. Motorola, 8 Mar. 2005.

Ford and William Topp. Assembly Language and Systems Programming for the M68000 Family - Second Edition. Lexington: D.C. Heath and Company. 1992.